HD HYUNDAI CONSTRUCTION EQUIPMENT HX55A CR SPECIFICATIONS

ENGINE				NIMAD / ATNIMOCCT			
Model				YANMAR / 4TNV86CT			
Emissions	certification			Tier 4 Final			
Output	SAE	J1995 (gross		47.6 hp (35.5 kW) @ 2,400 rpm			
		J1349 (net)		5.0 hp (33.6 kW) @ 2,40 7.6 (2,091)	10 rpm		
Piston disp		in ³ (d					
Number of		. ,					
Bore × Stro	ke	in (m	m) :	39" (86) × 3.54" (90)			
HYDRAU	ILIC SYST	EM					
Pump type	Э			Load sensing system			
Maximum f	low	gpm (ℓ/min	36.5 (138)			
HYDRAULI	CMOTORS						
Travel		Two fixed-d	Two fixed-displacement axial piston motors				
Swing		Fixed-displa	Fixed-displacement axial piston motor				
RELIEF VAL	VE SETTING	SS					
Implement	t circuits			3,613 (254)			
Travel circu	iit	psi	i (bar	r) 4,060 (285)			
Swing circu	iit			4,980 (350)			
HYDRAULI	C CYLINDER	S					
	Boom cylin	der		1-3.7" × 25.3" (95 × 643)			
Number	Arm cylinde	er		1-3.3" × 28.0" (85 × 710)			
of	Bucket cyl	inder		1-3.1" × 23.2" (80 × 590)			
cylinders- Bore ×	Boom swin	gcylinder	ir (mm	in 1-3.1" × 20.7" (80 × 525)			
diameter	Dozer cylir	ider	(111111)	1-4.5" × 8.3" (115 × 212) 1-4.5" × 8.3" (115 × 212)			
× stroke	Angle doze	ercylinder					
	Angle swin	g cylinder		1-3.7" × 13.2" (95 × 335)			
SWING S	VSTEM						
Swing moto			Fixed-displacement axial piston motor				
Swing redu			2-stage planetary				
Swing brak			Multi wet disc				
Swing spec		rpm	10.1				

TRAVEL S'	YSTEM						
Drive motor			Two fixed-displacement axial piston motors				
Drive metho	d		Fully hydrostatic type				
Reduction sy	/stem		2-stage planetary				
Max. travel	Low	mph (km/h)	1.6 (2.6)				
speed	High	mph (km/h)	2.9 (4.7)				
Max. drawba	rpull	lbf(kgf)	12,480 (5,662)				
Gradeability	degrees	6(%)	35° (70%)				
Parking brak	ie		Automatic, spring applied hydraulic released				
PILOT CON	ITROLS						
Two joystick	s with	Left hand	Arm and Swing				
one safety le	ever (ISO)	Right hand	Boom and Bucket (ISO)				
Traveling and	dsteering)	Two levers with pedals				
Engine throt	tle		Electric, dial type				
COOLANT	& LUBR	ICANT CAP	ACITY				
Fuel tank			33.0 (125)				
Engine coola	nt		3.0 (11.5)				
Engine oil		gal(<i>l</i>)	2.0 (7.4)				
Final drive (e	ach)		0.3 (1)				
Hydraulic tar	nk		11.6 (44)				
UNDERCA	RRAIGE						
	ollers on e	ach side	1				

OPERATING WEIGHT (APPROXIMATE)

No. of lower rollers on each side

Operating weight including 9'6" (2908 mm) boom 5' 5" (1,650 mm) long arm, SAE heaped 0.20 yd3 (0.15 m3) digging bucket 24" (606 mm) rubber track, lubricant, coolant, full fuel tank, full hydraulic tank, 1,430 lb (650 kg) counterweight and all standard equipment.

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Operating weight	lb (kg)	12,460 (5,650)
Ground pressure	psi (kgf/cm ²)	4.65 (0.33)

ENGINE	
Electronically controlled Yanmar engine	•
Double-element air filter	•
Auto-idling system	•
Water separator with filter	•
Electric fuel filler pump	0
HYDRAULIC SYSTEM	
Load-sensing hydraulic system	•
Two-speed travel with auto-shift	•
Floating dozer blade	•
Angle dozer blade	0
Proportional aux. control	•
2-way aux. hydraulic line for grapple	•
4-way aux. hydraulic line for rotating	0
Divert valve for 2-way hydraulic	•
Adjustable aux. flow on cluster	•
CABIN	
ROPS (Roll-Over Protective Structure, ISO3471)	•
OPS (Operator Protective Structure) Level 1	•
FOG (Falling Object Guard)	0
Adjustable mechanical suspension seat with leather cover	•
Retractable seatbelt with warning alarm	•
Heating and air conditioning	•
Travel levers with foot pedals	•

CABIN	
Emergency hammer for exit	•
Power-assisted front window	•
Rearview camera	0
Travel alarm	•
LED beacon lamp	0
5" digital cluster with IP68 water & dust proof	•
Radio with USB	•
12 V power socket	•
Side and rear mirrors	•
Cup holder	•
Pattern change valve inside cabin	•
Horn	•
CANOPY	
ROPS (Roll-Over Protective Structure, ISO3471)	
ROPS (ROII-OVER Protective Structure, 150547-1)	
OPS (Operator Protective Structure) Level 1	0
	0
OPS (Operator Protective Structure) Level 1	
OPS (Operator Protective Structure) Level 1 FOG (Falling Object Guard)	
OPS (Operator Protective Structure) Level 1 FOG (Falling Object Guard) Adjustable mechanical suspension seat	
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●: Standard / O: 0	Option
WORKING EQUIPMENT	
Compact radius	•
Boom swing function	•
Arm with thumb bracket	0
Standard arm 4' 7" (1,400 mm)	0
Long arm 5' 5" (1,650 mm)	•
Thumb bracket on arm	0
Hyundai quick coupler	0
Factory fit thumb	0
Quick coupler piping	0
Additional counterweight	0
Safety valves for boom/arm/dozer	0
Overload warning alarm	0
Travel and swivel motor with discs brake	•
1 LED work light on boom	•
2 LED work lights on cabin	0
UNDERCARRIAGE	
Rubber track 1' 4" (400 mm)	•
Steel track1' 4" (400 mm)	0
Interchangeability between rubber and steel track	•
TELEMATICS	
Hi MATE-Mobile (4G) Type	0

^{*} Standard and optional equipment may vary. Contact your Hyundai dealer for more information. The machine may vary according to International standards.

* The photos may include attachments and optional equipment that are not available in your area.

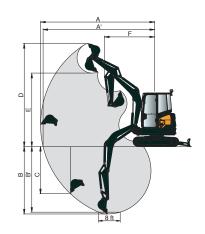
* Materials and specifications are subject to change without advance notice.

* All imperial measurements rounded off to the nearest pound or inch.

HX55A CR **DIMENSIONS & WORKING RANGE**



DIN	MENSIONS			
	Operating weight (cabin)	lb (kg)	12,460	(5,650)
Α	Overall length		18' 1"	(5,510)
В	Overall width		6'7"	(2,000)
	Overall width with dozer		6'7"	(2,000)
С	Overall height		8'5"	(2,555)
D	Overall width of upper structure		6' 1"	(1,850)
Е	Overall height of cab		8'5"	(2,555)
F	Ground clearance of counterweight		2'0"	(608)
G	Overall height of engine hood		5'3"	(1,605)
Н	Minimum ground clearance	ftin	0'8"	(215)
- 1	Rear-end swing radius	(mm)	3' 10"	(1,175)
J	Distance between tumblers		6'7"	(2,000)
K	Undercarriage length (without grou	ser)	8'3"	(2,515)
L	Undercarriage width		6'7"	(2,000)
М	Track gauge		5'3"	(1,600)
Ν	Track shoe width, standard		1' 4"	(400)
0	Height of blade		1'2"	(350)
Р	Ground clearance of blade up		1' 4"	(410)
Q	Depth of blade down (standard blade	e)	1' 11"	(580)
Q	Depth of blade down (angle blade)		2'2"	(670)
	Swing speed	rpm	1	0
	Gradeability	Degree (%)	35° (70%)
	Max traction force	lb (kg)	12,480	(5,662)



W	ORKING RANGE		LONG ARM	STD ARM
Α	Max digging reach		20'5 (6,230)	19' 8" (5,990)
A'	Max digging reach on ground		20"0 (6,100)	20' 2" (6,850)
В	Max digging depth	ft in (mm)	12'4 (3,750)	12' 6" (3,500)
B'	Max digging depth (8 ft level)		11'1 (3,380)	11' 2" (3,095)
С	Max vertical wall digging depth		9'6 (2,900)	8' 8" (2,650)
D	Max digging height		18"10 (5,740)	18' 10" (5,740)
Е	Max dumping height		13"3 (4,035)	13' 8" (4,865)
F	Min swing radius		8"6 (2,580)	8' 6" (2,580)

DIGGING FORCE			LONG ARM	LONG ARM NO Q/C
		kN	34	38
	SAE	kgf	3,506	3,835
Bucket digging force		lbf	7,730	8,454
bucket diggling force	ISO	kN	37	43
		kgf	3,789	4,340
		lbf	8,354	9,567
		kΝ	22	24
	SAE	kgf	2,271	2,392
Arm crowd force		lbf	5,007	5,273
Armerowarorce	ISO	kN	23	24
		kgf	2,308	2,457
		lbf	5,008	5,417

LIFTING CAPACITY

Cabin, 9' 2" (2.8 m) boom, 5' 5" (1.65 m) arm, 16" (400 mm) rubber track, no bucket, dozer down position. Rating over front H Rating over side or 360 degree

			Lift-point radius At maximum reach												
Lift-point height		3.3 ft ((1.0 m)	6.6 ft (2.0 m)	9.8 ft (3.0 m)	13.1 ft ((4.0 m)	16.4 ft ((5.0 m)	Capac	ity	Reach	
ft (m)		b	#	b	#	ŀ	#	b	45	b	#	b	#	ft (m)	
13.1 ft (4.0 m)	lb							*2,120	*2,120			*2,250	2,030	14.1 (4.30)	
15.110 (4.0111)	(kg)							*(960)	*(960)			*(1,020)	(920)	14.1 (4.50)	
9.8 ft (3.0 m)	lb							*2,140	*2,140			*2,160	1,610	16.2 (4.95)	
9.010 (3.0111)	(kg)							*(970)	*(970)			*(980)	(730)	10.2 (4.93)	
6.6 ft (2.0 m)	lb					*3,260	*3,260	*2,560	2,200	*2,270	1,570	*2,120	1,430		
0.011 (2.0111)	(kg)					*(1,480)	*(1,480)	*(1,160)	(1,000)	*(1,030)	(710)	*(960)	(650)		
3.3 ft (1.0 m)	lb					*4,670	3,200	*3,090	2,120	*2,470	1,520	*2,230	1,390	17.6 (5.36)	
3.310(1.0111)	(kg)					*(2,120)	(1,450)	*(1,400)	(960)	*(1,120)	(690)	*(1,010)	(630)	17.0 (3.30)	
0.0 ft (0.0 m)	lb					*5,290	3,090	*3,440	2,050	*2,560	1,500	*2,400	1,430	17.1 (5.20)	
0.010 (0.0111)	(kg)					*(2,400)	(1,400)	*(1,560)	(930)	*(1,160)	(680)	*(1,090)	(650)	17.1 (3.20)	
-3.3 ft (-1.0 m)	lb	*4,010	*4,010	*5,250	*5,250	*5,110	3,060	*3,400	2,030			*2,490	1,590	15.7 (4.79)	
3.310(-1.0111)	(kg)	*(1,820)	*(1,820)	*(2,380)	*(2,380)	*(2,320)	(1,390)	*(1,540)	(920)			*(1,130)	(720)	15.7 (4.79)	
-6.6 ft (-2.0 m)	lb	*6,990	*6,990	*7,010	6,170	*4,170	3,110	*2,510	2,070			*2,490	2,070	13.2 (4.01)	
-6.611 (-2.011)	(kg)	*(3,170)	*(3,170)	*(3,180)	(2,800)	*(1,890)	(1,410)	*(1,140)	(940)			*(1,130)	(940)	13.2 (4.01)	

- Lifting capacities are based on ISO 10567.
 Lifting capacities of HX-A series do not exceed 75% of tipping load with the machine on firm, level ground or 87% of full hydraulic capacity.
 The lift-point is bucket pivot mounting pin on the arm (without bucket mass).
- 4. (*) indicates load limited by hydraulic capacity.

Specifications and features are subject to change without notice.

